

InterActive Feature Selection

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Abstract

We study the effects of feature selection and human feedback on features in active learning settings. Our experiments on a variety of text categorization tasks indicate that there is significant potential in improving classifier performance by feature reweighting, beyond that achieved via selective sampling alone (standard active learning) if we have access to an *oracle* that can point to the important (most predictive) features. Consistent with previous findings, we find that feature selection based on the labeled training set has little effect. But our experiments on human subjects indicate that human feedback on feature relevance can identify a sufficient proportion (65%) of the most relevant features. Furthermore, these experiments show that feature labeling takes much less (about 1/5th) time than document labeling. We propose an algorithm that interleaves labeling features and documents which significantly accelerates active learning.

1 Introduction

A major bottleneck in machine learning applications is the lack of sufficient labeled data for adequate classifier performance, as manual labeling is often tedious and costly. Techniques such as active learning, semi-supervised learning, and transduction have been pursued with considerable success in reducing labeling requirements. In the standard active learning paradigm, learning proceeds sequentially, with the learning algorithm actively asking for the labels of instances from a teacher. The objective is to ask the teacher to label the most informative instances in order to reduce labeling costs and accelerate the learning. There has been very little work in supervised learning in which the user (teacher) is queried on aspects other than class assignment of instances. In experiments in this paper we study the benefits and costs of feature feedback via humans on active learning. To this end we pick document classification [Sebastiani, 2002] as the learning problem of choice because it represents a case of supervised learning which traditionally relies on example documents as input for training and where users have sufficient

prior knowledge on features which can be used to accelerate learning. For example, to find documents on the topic *cars* in traditional supervised learning the user would be required to provide sufficient examples of *cars* and *non-cars* documents. However, this is not the only way in which the information need of a user looking for documents on *cars* can be satisfied. In the *information retrieval* setting the user would be asked to issue a query, that is, state a few words (features) indicating her information need. Thereafter, feedback which may be at a term or at a document level may be incorporated. In fact, even in document classification, a user may use a keyword based search to locate the initial training examples. However, traditional supervised learning tends to ignore the prior knowledge that the user has, once a set of training examples have been obtained. In this work we try to find a marriage between approaches to incorporating user feedback from machine learning and information retrieval and show that active learning should be a dual process – at the term and at the document-level. This has applications in email filtering and news filtering where the user has some prior knowledge and a willingness to label some (as few as possible) documents in order to build a system that suits her needs. We show that humans have good intuition for important features in text classification tasks since features are typically words that are perceptible to the human and that this human prior knowledge can indeed accelerate learning.

In summary, our contributions are: (1) We demonstrate that access to a feature importance oracle can improve performance ($F1$) significantly over uncertainty sampling. (2) We show that even naive users can provide feedback on features with about 60% accuracy of the oracle. (3) We show that the relative manual costs of labeling features is about 1/5th that of document feedback. (4) We show a method of simultaneously soliciting class labels and feature feedback that improves classifier performance significantly.

We describe the experimental setup in Sec. 2 and show how feature selection using an oracle is useful to active learning in Sec. 3. In Sec. 4 we show that humans can indeed identify useful features and show how human-chosen features can be used to accelerate learning in Sec. 5. We relate our work to past work in Sec. 6 and outline directions for the future in section Sec. 7.

*This work was done in part when the author was at Yahoo! Inc.

2 Experimental setup

Our test bed for this paper comes from three domains:

(1) The 10 most frequent classes from the Reuters-21578 corpus (12902 documents). (2) The 20-Newsgroups corpus (20000 documents from 20 Usenet newsgroups). (3) The first 10 topics from the TDT-2001 corpus (67111 documents in 3 languages from broadcast and news-wire sources).

For all three corpora we consider each topic as a *one versus all* classification problem. We also pick two binary classification problems viz., *Baseball vs Hockey* and *Automobiles vs Motorcycles* from the 20-Newsgroups corpus. In all we have 42 classification problems.¹ All the non-english stories in the TDT corpus were machine translated into English. As features we use words, bigrams and trigrams obtained after stopping and stemming with the Porter stemmer in the Rainbow Toolkit [McCallum, 1996]

We use linear support vector machines (SVMs) and uncertainty sampling for active learning [Scholkopf and Smola, 2002; Lewis and Catlett, 1994]. SVMs are the state of art in text categorization, and have been found to be fairly robust even in the presence of many redundant and irrelevant features [Brank *et al.*, 2002; Rose *et al.*, 2002]. Uncertainty sampling [Lewis and Catlett, 1994] is a type of active learning in which the example that the user (teacher) is queried on is the unlabeled instance that the classifier is most uncertain about. When the classifier is an SVM, unlabeled instances closest to the margin are chosen as queries [Tong and Koller, 2002]. The active learner may have access to all or a subset of the unlabeled instances. This subset is called the pool and we use a pool size of 500 in this paper. The newly labeled instance is added to the set of labeled instances and the classifier is retrained. The user is queried a total of T times.

The *Deficiency* metric [Baram *et al.*, 2003] quantifies the performance of the querying function for a given active learning algorithm. Originally deficiency was defined in terms of accuracy. Accuracy is a reasonable measure of performance when the positive class is a sizeable portion of the total. Since this is not the case for all the classification problems we have chosen, we modify the definition of deficiency, and define it in terms of the $F1$ measure (harmonic mean of precision and recall [Rose *et al.*, 2002]). Using notation similar to the original paper [Baram *et al.*, 2003], let \mathcal{U} be a random set of P labeled instances, $F1_t(RAND)$ be the average $F1$ achieved by an algorithm when it is trained on t randomly picked examples and $F1_t(ACT)$ be the average $F1$ obtained using t actively picked examples. Deficiency \mathcal{D} is defined as:

$$\mathcal{D}_T = \frac{\sum_{t=init}^T (F1_M(RAND) - F1_t(ACT))}{\sum_{t=init}^T (F1_M(RAND) - F1_t(RAND))} \quad (1)$$

$F1_M(RAND)$ is the $F1$ obtained with a large number (M) of randomly picked examples. For this paper we take $M = 1000$ and $t = 2, 7, \dots, 42$. When $t = 2$ we have one positive and one negative example. $F1_t(\bullet)$ is the average $F1$ computed over 10 trials. In addition to deficiency we report $F1_t$ for some values of t . Intuitively, if C_{act} is the curve

obtained by plotting $F1_t(ACT)$, C_{rand} is the corresponding curve using random sampling and C_M is the straight line $F1_t = F1_M$ then deficiency is the ratio of the area between C_{act} and C_M and the area between C_{rand} and C_M . The lower the deficiency the better the active learning algorithm. We aim to minimize deficiency and maximize $F1$.

3 Oracle Feature Selection Experiments

The oracle in our experiments has access to the labels of all P documents in \mathcal{U} and uses this information to return a list of the k most important features. We assume that the parameter k is input to the oracle. The oracle orders the k features in decreasing information gain order. Given a set of k features we can perform active learning as discussed in the previous section and plot C_{act} for each value of k .

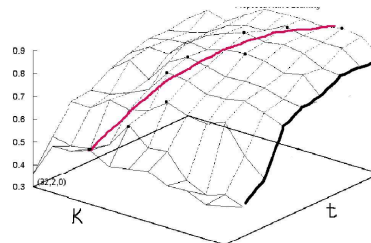


Figure 1: Average $F1_t(ACT)$ for different values of k . k is the number of features and t is the number of documents.

Figure 1 shows a plot of $F1_t(ACT)$ against number of features k and number of labeled training examples t , for the *Earnings* category in Reuters. The x , y and z axes denote k , t and $F1$ respectively. The number of labeled training examples t ranges from 2...42 in increments of 5. The number of features used for classification k has values from 32 to 33718 (all features). The dark dots represent the maximum F_t for each value of t , while the dark band represents the case when all features are used. This method of learning in one dimension is representative of traditional active learning. Clearly when the number of documents is few, performance is better when there is a smaller number of features. As the number of documents increases the number of features needed to achieve best accuracy increases. From the figure it is obvious that we can get a big boost in accuracy by starting with fewer features and then increasing the complexity of the model (the number of relevant features) as the number of labeled documents increase.

All 42 of our classification problems exhibit behavior like that in Figure 1 [Raghavan *et al.*, 2005]. We report the average deficiency, $F1_7$ ($F1$ score with 7 labeled examples) and $F1_{22}$ in Fig. 2 to illustrate this point. The column labeled *Act* shows performance using traditional active learning and all the features. The column labeled *Ora* shows performance obtained using a reduced subset of features using the Oracle.

Intuitively, with limited labeled data, there is little evidence to prefer one feature over another. Feature/dimension reduction (by the oracle) allows the learner to “focus” on dimensions that matter, rather than being “overwhelmed” with

¹<http://www.daviddlewis.com/resources/testcollections/reuters21578/>, <http://kdd.ics.uci.edu/databases/20newsgroups/20newsgroups.html>, <http://www ldc.upenn.edu/Projects/TDT3/>

Class ↓	\mathcal{D}_{42}		$F1_7$		$F1_{22}$		$F1_{1000}$
	Act	Oracle	Act	Ora	Act	Ora	Act
Reuters	0.421	0.319	0.345	0.446	0.569	0.621	0.727
20-News.	0.602	0.344	0.072	0.222	0.21	0.29	0.446
TDT	0.735	0.656	0.186	0.290	0.282	0.407	0.751
Bas. vs Hock	0.710	0.447	0.587	0.701	0.785	0.828	0.963
Auto vs Mot.	0.676	0.321	0.431	0.724	0.758	0.860	0.899

Figure 2: Improvements in deficiency, $F1_7$ and $F1_{22}$ using an oracle to select the most important features. Remember that the objective is to minimize deficiency and maximize $F1$. For each of the three metrics, figures in bold are statistically significant improvements over Uncertainty sampling using all features (the corresponding columns denoted by Act). When 1000 documents are labeled ($F1_{1000}$) using the entire feature set leads to better $F1$ scores.

numerous dimensions right at the outset of learning. As the number of labeled examples increases, feature selection becomes less important, as the learning algorithm becomes more capable of finding the discriminating hyperplane (feature weights). We experimented with filter based methods for feature selection, which did not work very well (i.e., tiny or no improvements). This is expected given such limited training set sizes (see Fig. 3), and is consistent with most previous findings [Sebastiani, 2002]. Next we determine if humans can identify these *important features*.

4 Human Labeling

Consider our introductory example of a user who wants to find all documents that discuss *cars*. From a human perspective the words ‘car’, ‘auto’ etc may be important features in documents discussing this topic. Given a large number of documents labeled as on-topic and off-topic, and given a classifier trained on these documents, the classifier may also find these features to be most relevant. With little labeled data (say 2 labeled examples) the classifier may not be able to determine the discriminating features. While in general in machine learning the source of labels is not important to us, in active learning scenarios in which we expect the labels to come from humans we have valid questions to pose: (1) Can humans label features as well as documents? (2) If the labels people provide are noisy through being inconsistent, can we learn well enough? (3) Are features that are important to the classifier perceptible to a human?

Our concern in this paper is asking people to give feedback on features, or word n-grams, as well as entire documents. We may expect this to be more efficient, since documents contain redundancy, and results from our oracle experiments indicate great potential. On the other hand, we also know that synthetic examples composed of a combination of real features can be difficult to label [Baum and Lang, 1992].

4.1 Experiments and Results

In order to answer the above questions we conducted the following experiment. We picked 5 classification problems which we thought were perceptible to the average person on the street and also represented the broad spectrum of problems from our set of 42 classification problems. We took the two binary classification problems and from the remaining 40 one-versus-all problems we chose three (*earnings*, *hurricane Mitch* and *talk.politics.mideast*). For a given classification

problem we took the top 20 features as ranked by information gain on the entire labeled set. In this case we did not stem the data so that features remain as legitimate English words. We randomly mix these with features which are much lower in the ranked list. We show each user one feature at a time and give them two options – *relevant* and *not-relevant/don’t know*. A feature is relevant if it helps discriminate the positive or the negative class. We measure the time it takes the user to label each feature. We do not show the user all the features as a list, though this may be easier, as lists provide some context and serve as a summary. Hence our method provides an upper bound on the time it takes a user to judge a feature. We compare this with the time it takes a user to judge a document. We measure the precision and recall of the user’s ability to label features. We ask the user to first label the features and then documents, so that the feature labeling process receives no benefit due to the fact that the user has viewed relevant documents. In the learning process we have proposed, though, the user would be labeling documents and features simultaneously, so the user would indeed be influenced by the documents he reads. Hence our method is more stringent than the real case. We could in practice ask users to highlight terms as they read documents. Experiments in this direction have been conducted in information retrieval [Croft and Das, 1990].

Our users were six graduate students and two employees of a company, none of whom were authors of this paper. Of the graduate students, five were in computer science and one from public health. All our users were familiar with the use of computers. Five users understood the problem of document classification but none had worked with these corpora. One of our users was not a native speaker of English. The topics were distributed randomly, and without considering user expertise, so that each user got an average of 2-3 topics. There were overlapping topics between users such that each topic was labeled by 2-3 users on average. A feedback form asking the users some questions about the difficulty of the task was handed out at the end.

We evaluated user feature labeling by calculating their average precision and recall at identifying the top 20 features as ranked by an oracle using information gain on the entire labeled set. Fig. 3 shows these results. For comparison we have also provided the precision and recall (against the same oracle ranking of top 20 features) obtained using 50 labeled examples (picked using uncertainty sampling) denoted by @50.

Class Problem	Prec.		Rec.		Avg. Time (secs)	
	Hum.	@50	Hum.	@50	Feat.	Docs
Baseball..	0.42	0.3	0.7	0.3	2.83	12.6
Auto vs ...	0.54	0.25	0.81	0.25	3.56	19.84
Earnings	0.53	0.2	0.66	0.25	2.97	13
...midwest	0.68	0.35	0.55	0.35	2.38	12.93
...Mitch	0.716	0.65	0.56	0.65	2.38	13.19
Average	0.580	0.35	0.65	0.38	2.82	14.31

Figure 3: Ability of users to identify important features. Precision and Recall against an oracle, of users (Hum.) and an active learner which has seen 50 documents (@50). Average labeling times for features and documents are also shown. All numbers are averaged over users.

Precision and Recall of the humans is high, supporting our hypothesis that features that a classifier finds to be relevant after seeing a large number of labeled instances are obvious to a human after seeing little or no labeled data (the latter case being true of our experiments). Additionally the Precision and Recall @50 is significantly lower than that of humans, indicating that a classifier like an SVM needs to see much more data before it can find the discriminatory features.

The last column of Fig. 3 shows time taken for labeling features and documents. On average humans require about 5 times longer to label documents than to label features. Note that features may be even easier to label if they are shown in context – as lists, with relevant passages etc. There are several other metrics and points of discussion such as user expertise, time taken to label relevant and non-relevant features and so on, which we reserve for future work. One important consideration though, is that document length influences document labeling time. We found the two to be correlated by $r = 0.289$ which indicates a small increase in time for a large increase in length. The standard deviations for precision and recall are 0.14 and 0.15 respectively. Different users vary significantly in precision, recall and the total number of features labeled relevant. Based on feedback on a post-labeling survey we are inclined to believe that this is due to individual caution exercised during the labeling process.

Some of the highlights of the post-labeling survey are as follows. On average users found the ease of labeling features to be 3.8 (where 0 is most difficult and 5 is very easy) and documents 4.2. In general users with poor prior knowledge found the feature labeling process very hard, although as we will show, their labels were extremely useful to the classifier. The average expertise (5=expert) was 2.4, indicating that most users felt they had little domain knowledge for the tasks they were assigned. We now proceed to see how to use features labeled as relevant by our naive users in active learning.

5 A Human in the Loop

We saw in Sec. 3 that feature selection coupled with uncertainty sampling gives us big gains in performance when there are few labeled examples. In Sec. 4 we saw that humans can discern discriminative features with reasonable accuracy. We now describe our approach of applying term and document level feedback simultaneously in active learning.

5.1 InterActive Learning Algorithm

Let documents be represented as vectors $X_i = x_{i1} \dots x_{i|F|}$, where $|F|$ is the total number of features. At each iteration the active learner not only queries the user on an uncertain document, but also presents a list of f features and asks the user to label features which she considers relevant. The features to be displayed to the user are the top f features obtained by ordering the features by information gain. To obtain the information gain values with t labeled instances we trained a classifier on these t labeled instances. Then to compute information gain, we used the 5 top ranked (farthest from the margin) documents from the unlabeled set in addition to the t labeled documents. Using the unlabeled data for term level feedback is very common in information retrieval and is called pseudo-relevance feedback [Salton, 1968].

The user labels some of the f features which he considers discriminative features. Let $\vec{s} = s_1 \dots s_{|F|}$ be a vector containing weights of relevant features. If a feature number i that is presented to the user is labeled as relevant then we set $s_i = a$, otherwise $s_i = b$, where a and b are parameters of the system. The vector \vec{s} is noisier than the real case because in addition to mistakes made by the user we lose out on those features that the user might have considered relevant, had he been presented that feature when we were collecting relevance judgments for features. In a real life scenario this might correspond to the lazy user who labels few features as relevant and leaves some features unlabeled in addition to making mistakes. If a user had labeled a feature as relevant in some past iteration we don't show the user that feature again.

We incorporate the vector \vec{s} as follows. For each X_i in the labeled and unlabeled sets we multiply x_{ij} by s_j to get X'_{ij} . In other words we scale all relevant features by a and non-relevant features by b . We set $a = 10$ and $b = 1$.²

By scaling the important features by a we are forcing the classifier to assign higher weights to these features. We demonstrate this with the following example. Consider a linear SVM, $|F| = 2$ and 2 data points $X_1 = (1, 2)$ and $X_2 = (2, 1)$ with labels $+1$ and -1 respectively. An SVM trained on this input learns a classifier with $w = (-0.599, +0.599)$. Thus both features are equally discriminative. If feature 1 is considered more discriminative by a user, then by our method $X'_1 = (10, 2)$ and $X'_2 = (20, 1)$ and $w' = (0.043, -0.0043)$, thus assigning higher weight to f_1 . Now, this is a "soft" version of the feature selection mechanism of Sec. 3. But in that case the Oracle knew the ideal set of features; we can view those set of experiments as a special case where $b = 0$. We expect that human labels are noisy and we do not want to zero-out potentially relevant features.

5.2 Experiments and Results

To make our experiments repeatable (to compute average performance and for convenience) we simulate user interaction as follows. For each classification problem we maintain a list of features that a user might have considered relevant had he

²We picked our algorithm's parameters based on a preliminary test on 3 topics (baseball, earnings, and acquisitions) using the oracle features of Sec. 3.

been presented that feature. For these lists we used the judgments obtained in Sec. 4. Thus for each of the 5 classification problems we had 2-3 such lists, one per user who judged that topic. For the 10 TDT topics we have topic descriptions as provided by the LDC, and we simulated explicit human feedback on feature relevance as follows: The topic descriptions contain names of people, places and organizations that are key players in this topic in addition to other keywords. We used the words in these topic descriptions as the list of relevant features. Now, given these lists we can perform the simulated HIL (*Human in the Loop*) experiments for 15 classification problems. At each iteration f features are shown to the user. If the feature exists in the list of relevant features, we set the corresponding bit in \vec{s} and proceed with the active learning as in Sec. 5.1. Fig. 4 shows the performance of the HIL experiments. As before we report deficiency, $F1_7$ and $F1_{22}$. As a baseline we also report results for the case when the top 20 features as obtained by the information gain oracle are input to the simulated HIL experiments (this represents what a user with 100% precision and recall would obtain by our method). The Oracle is (as expected) much better than plain uncertainty sampling, on all 3 measures, reinforcing our faith in the algorithm of Sec. 5.1. The performance of the HIL experiments is almost as good as the Oracle, indicating that user input (although noisy) can help improve performance significantly. The only relative poor performance for the HIL simulation is on the average \mathcal{D}_{42} measure for the TDT categories, where we used all the words from the topic descriptions as a proxy for explicit human feedback on features. The plot on the right is of $F1_t(HIL)$ for *hurricane Mitch*. As a comparison $F1_t(ACT)$ is shown. The HIL values are much higher than for plain uncertainty sampling.

We also observed that relevant features were usually spotted in very early iterations. For the *Auto vs Motorcycles* problem, the user has been asked to label 75% (averaged over multiple iterations and multiple users) of the oracle features at some point or the other. The most informative words (as determined by the Oracle) – *car* and *bike* are asked of the user in very early iterations. The label for *car* is always (100% of the times) asked, and 70% of the time the label for this word is asked of the user in the first iteration itself. This is closely followed by the word *bike* which the user is queried on within the first 5 iterations 80% of the time. Most relevant features are queried within 10 iterations which makes us believe that we can stop feature level feedback in 10 iterations or so. When to stop asking questions on both features and documents and switch entirely to documents remains an area for future work.

6 Related Work

Our work is related to a number of areas including query learning, active learning, use of (prior) knowledge and feature selection in machine learning, term-relevance feedback in information retrieval, and human-computer interaction, from which we can cite only a few.

Our proposed method is an instance of query-based learning and an extension of standard (“pool-based”) active learning which focuses on selective sampling of instances (from

a pool of unlabeled data) alone [Cohn *et al.*, 1994]. Although query-based learning can be very powerful in theory [Angluin, 1992], arbitrary queries may be difficult to answer in practice [Baum and Lang, 1992], hence the popularity of pool-based methods, and the motivation for studying the effectiveness and ease of predictive feature identification by humans in our application area. That human prior knowledge can accelerate learning has been investigated by [Pazani and Kibler, 1992], but our work differs in techniques (they use prior knowledge to generate horn-clause rules) and applications. [Beineke *et al.*, 2004] uses human prior knowledge of co-occurrence of words to improve classification of product reviews. None of this work, however, considers the use of prior knowledge in the active learning setting. Our work is unique in the field of active learning as we extend the query model to include feature as well as document level feedback. Our study of the human factors (such as quality of feedback and costs) is also a major differentiating theme between our work and previous work in incorporating prior knowledge which did not address this issue, or might have assumed experts in machine learning taking a role in training the system [Schapire *et al.*, 2002; Wu and Srihari, 2004; Godbole *et al.*, 2004]. We only assume knowledge about the topic of interest. Our algorithmic techniques and the studied modes of interaction differ and are worth further comparison.

In both [Wu and Srihari, 2004; Schapire *et al.*, 2002], prior knowledge is given at the outset which leads to a “soft” labeling of the labeled or unlabeled data that is incorporated into training via modified boosting or SVM training. However, in our scheme the user is labeling documents and features simultaneously. We expect that our proposed interactive mode has an advantage over requesting prior knowledge from the outset, as it may be easier for the user to identify/recall relevant features while labeling documents in the collection and being presented with candidate features. The work of [Godbole *et al.*, 2004] puts more emphasis on system issues and focuses on multi-class training rather than a careful analysis of effects of feature selection and human efficacy. Their proposed method is attractive in that it treats features as single term documents that can be labeled by humans, but they also study labeling features before documents (and only in an “oracle” setting, *i.e.*, not using actual human annotators), and do not observe much improvements using their particular method over standard active learning in the single domain (Reuters) they test on.

7 Conclusions and Future Work

We showed experimentally that for learning with few labeled examples, good feature selection is extremely useful. As the number of examples increases, the vocabulary (feature set size) of the system also needs to increase. A teacher, who is not knowledgeable in machine learning, can help accelerate training the system in this early stage, by pointing out potentially important words. We also conducted a user study to see how well naive users performed as compared to a feature oracle. We used our users’ outputs in realistic *human in the loop* experiments and found significant increase in performance.

This paper raises the question of what questions (other than

Dataset	\mathcal{D}_{42}			$F1_7$			$F1_{22}$		
	Act	Oracle	HIL	Act	Oracle	HIL	Act	Oracle	HIL
Baseball	0.71	0.41	0.46	0.49	0.63	0.60	0.63	0.79	0.70
Earnings	0.90	0.64	0.64	0.61	0.79	0.73	0.80	0.85	0.86
Auto vs Motor	0.82	0.33	0.60	0.35	0.62	0.60	0.71	0.83	0.73
Hurr. Mitch	0.89	0.38	0.38	0.04	0.46	0.60	0.08	0.63	0.58
talk.politics.mideast	0.49	0.28	0.28	0.14	0.28	0.29	0.32	0.49	0.49
Avg TDT performance	0.86	0.77	0.89	0.09	0.21	0.24	0.18	0.32	0.22

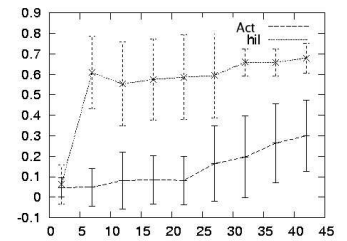


Figure 4: Improvement in deficiency due to human feature selection. Numbers for HIL are averaged over users. The graph shows Human Feature Selection for Hurricane Mitch with the x-axis being the number of labeled documents and y-axis $F1(HIL)$; the difference between these two curves is summarized by the deficiency score. The $F1_7$ and $F1_{22}$ scores show the points on the two curves where 7 and 22 documents have been labeled with active learning. The difference between no feature feedback and human-labeled features is greatest with few documents labeled, but persists up to 42 documents labeled.

questions about the labels of instances) an active learner can ask a user about the domain in order to learn as quickly as possible. In our case, the learner asked the teacher queries on the relevancy of words in addition to the labels of documents. Both types of questions were easy for the teacher to understand. Our subjects did indeed find marking words without context a little hard, and suggested that context might have helped. We intend to conduct a user study, to see what users can perceive easily, and to incorporate these into learning algorithms.

Acknowledgments

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